

# Characteristic polynomial

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# Characteristic polynomial

## Definitin and Examples

In this section we deal with the characteristic polynomial of an  $n$  by  $n$  matrix  $A$ , which is a polynomial of degree  $n$ , from which we give a practical way to find the eigenvalues of  $A$ .

### Definition

Let  $A \in \mathcal{M}_n(\mathbb{R})$  be a square matrix. The characteristic polynomial of  $A$  is the polynomial of degree  $n$  given by  $p_A(x) = \det(A - xI_n)$ , where  $I_n$  is the identity  $n$  by  $n$  matrix<sup>a</sup>.

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<sup>a</sup>In some references the characteristic polynomial of  $A$  is the polynomial of degree  $n$  given by  $p_A(x) = \det(xI_n - A)$ .

We simply write

$$p_A(x) = \det(A - xI).$$

Note that if  $A$  is an  $n$  by  $n$  matrix given by

$$A = \begin{pmatrix} a_{11} & a_{12} & a_{13} & \dots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \dots & a_{2n} \\ a_{31} & a_{32} & a_{33} & \dots & a_{3n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & a_{n3} & \dots & a_{nn} \end{pmatrix},$$

then

$$p_A(x) = \begin{vmatrix} \boxed{a_{11} - x} & a_{12} & a_{13} & \dots & a_{1n} \\ a_{21} & \boxed{a_{22} - x} & a_{23} & \dots & a_{2n} \\ a_{31} & a_{32} & \boxed{a_{33} - x} & \dots & a_{3n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & a_{n3} & \dots & \boxed{a_{nn} - x} \end{vmatrix}$$

- Clearly,  $p_A(x)$  is always a polynomial of **degree**  $n$  and by the Fundamental Theorem of Algebra (**FTA**), this polynomial has  $n$  roots.

## Definition

The roots of  $p_A(x)$  are called **eigenvalues** of  $A$ . Also, we have the notation:

$$Sp(A) = \{\lambda \in \mathbb{R} \text{ or } \mathbb{C} ; \lambda \text{ is an eigenvalue of } A\},$$

which is called the **spectral set** of  $A$ . So,  $\lambda \in Sp(A) \Leftrightarrow p_A(\lambda) = 0$ .

## Example

Calculate the characteristic polynomial of the following matrix:

$$A = \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix}.$$

From definition, we obtain

$$\begin{aligned} p_A(x) &= \begin{vmatrix} 2-x & 1 \\ 1 & 2-x \end{vmatrix} = (2-x)^2 - 1 \\ &= x^2 - 4x + 3 \end{aligned}$$

We can easily see that  $p_A(x) = (1-x)(3-x)$ , and so  $Sp(A) = \{1, 3\}$ .

## Example

Calculate the characteristic polynomial of the following matrix:

$$A = \begin{pmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{pmatrix}.$$

By definition,

$$\begin{aligned} p_A(x) &= \begin{vmatrix} 2-x & 1 & 1 \\ 1 & 2-x & 1 \\ 1 & 1 & 2-x \end{vmatrix} \\ &= (2-x) \left[ (2-x)^2 - 1 \right] - (2-x-1) + (1-2+x) \\ &= -x^3 + 6x^2 - 9x + 4. \end{aligned}$$

So, we can take  $p_A(x) = x^3 - 6x^2 + 9x - 4$ .

For computing the eigenvalues of  $A$ , we must factorize  $x^3 - 6x^2 + 9x - 4$ . So the above method for computing  $p_A(x)$  is **not useful**. For this purpose, it is natural to ask the following question:

## Problem

How to **compute** and **factorize**  $p_A(x)$  at the same time?

Let us take the matrix  $A = \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix}$ . Then

$$\begin{aligned} p_A(x) &= \begin{vmatrix} 2-x & 1 \\ 1 & 2-x \end{vmatrix} \begin{array}{c} c_1 \\ \downarrow \\ c_1 + c_2 \end{array} \quad (\text{the first column } c_1 \text{ becomes } c_1 + c_2) \\ &= \begin{vmatrix} (3-x) & 1 \\ (3-x) & 2-x \end{vmatrix} = (3-x) \begin{vmatrix} 1 & 1 \\ 1 & 2-x \end{vmatrix} = (3-x)(2-x-1) \\ &= (3-x)(1-x). \end{aligned}$$



## Example

Consider the matrix  $A = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix}$ . In the same manner, we get

$$\begin{aligned} p_A(x) &= \begin{vmatrix} 1-x & 1 & 1 \\ 1 & 1-x & 1 \\ 1 & 1 & 1-x \end{vmatrix} = \begin{vmatrix} -x & 0 & 1 \\ x & -x & 1 \\ 0 & x & 1-x \end{vmatrix} \\ &= x^2 \begin{vmatrix} + & - & + \\ -1 & 0 & 1 \\ 1 & -1 & 1 \\ 0 & 1 & 1-x \end{vmatrix} = x^2 [-(x-1-1) + (1-0)] \\ &= x^2(3-x). \end{aligned}$$

Hence,  $p_A(x) = x^2(3-x)$ , and so  $Sp(A) = \{0, 3\}$ .

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### Example

Calculate the characteristic polynomial of the following matrix:

$$A = \begin{pmatrix} 7 & -6 & -2 \\ 2 & 0 & -1 \\ 2 & -3 & 2 \end{pmatrix}.$$

It is clear that

$$\begin{aligned} p_A(x) &= \begin{vmatrix} 7-x & -6 & -2 \\ 2 & -x & -1 \\ 2 & -3 & 2-x \end{vmatrix} \quad \begin{array}{l} c_1 \\ \downarrow \\ 2 \times c_3 + c_1 \end{array} \\ &= \begin{vmatrix} (3-x) & -6 & -2 \\ 0 & -x & -1 \\ 2(3-x) & -3 & 2-x \end{vmatrix} \end{aligned}$$

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Therefore,

$$\begin{aligned} p_A(x) &= (3-x) \begin{vmatrix} 1 & -6 & -2 \\ 0 & -x & -1 \\ 2 & -3 & 2-x \end{vmatrix} \begin{array}{l} c_2 \\ \downarrow \\ 3 \times c_3 - c_2 \end{array} \\ &= (3-x) \begin{vmatrix} 1 & 0 & -2 \\ 0 & -(3-x) & -1 \\ 2 & 3(3-x) & 2-x \end{vmatrix} = (3-x)^2 \begin{vmatrix} + & - & + \\ 1 & 0 & -2 \\ 0 & -1 & -1 \\ 2 & 3 & 2-x \end{vmatrix} \\ &= (3-x)^2 (-2 + x + 3 - 2(2)) \\ &= (x-3)^3. \end{aligned}$$

That is,  $p_A(x) = (x-3)^3$ .

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### Example

Calculate the characteristic polynomial of each of the following matrices:

$$A_1 = \begin{pmatrix} 4 & 2 & -1 \\ 2 & 7 & -2 \\ -1 & -2 & 4 \end{pmatrix}, \quad A_2 = \begin{pmatrix} 13 & -12 & -6 \\ 6 & -5 & -3 \\ 18 & -18 & -8 \end{pmatrix}$$

$$A_3 = \begin{pmatrix} 1 & -1 & -1 \\ -1 & 1 & -1 \\ -1 & -1 & 1 \end{pmatrix}, \quad A_4 = \begin{pmatrix} 4 & 1 & -1 \\ 2 & 5 & -2 \\ 1 & 1 & 2 \end{pmatrix}$$

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### Example

(i) From the definition of the characteristic polynomial, we get

$$\begin{aligned} p_{A_1}(x) &= \det(A_1 - xI_3) \\ &= \begin{vmatrix} 4-x & 2 & -1 \\ 2 & 7-x & -2 \\ -1 & -2 & 4-x \end{vmatrix} && \begin{array}{l} 1^{\text{st}} \text{ column} \\ \downarrow \\ 1^{\text{st}} + 3^{\text{rd}} \end{array} \\ &= \begin{vmatrix} (3-x) & 2 & -1 \\ 0 & 7-x & -2 \\ (3-x) & -2 & 4-x \end{vmatrix} \\ &= (3-x) \begin{vmatrix} 1 & 2 & -1 \\ 0 & 7-x & -2 \\ 1 & -2 & 4-x \end{vmatrix} && \begin{array}{l} 2^{\text{nd}} \text{ column} \\ \downarrow \\ 2 \times 3^{\text{rd}} + 2^{\text{nd}} \end{array} \end{aligned}$$

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That is,

$$\begin{aligned} p_{A_1}(x) &= (3-x) \begin{vmatrix} 1 & 0 & -1 \\ 0 & 3-x & -2 \\ 1 & 2(3-x) & 4-x \end{vmatrix} = (3-x)^2 \begin{vmatrix} + & - & + \\ 1 & 0 & -1 \\ 0 & 1 & -2 \\ 1 & 2 & 4-x \end{vmatrix} \\ &= (3-x)^2 [4-x+4-(0-1)] \\ &= (3-x)^2 (9-x). \end{aligned}$$

That is,  $p_{A_1}(x) = (3-x)^2(9-x)$ , and so  $Sp(A) = \{3, 9\}$ .

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### Example

(ii) Compute  $p_{A_2}(x)$  :

$$\begin{aligned} p_{A_2}(x) &= \begin{vmatrix} 13-x & -12 & -6 \\ 6 & -5-x & -3 \\ 18 & -18 & -8-x \end{vmatrix} && c_1 \rightarrow c_1 + c_2 \\ &= \begin{vmatrix} (1-x) & -12 & -6 \\ (1-x) & -5-x & -3 \\ 0 & -18 & -8-x \end{vmatrix} && c_2 \rightarrow (-2) \times c_3 + c_2 \\ &= \begin{vmatrix} (1-x) & 0 & -6 \\ (1-x) & (1-x) & -3 \\ 0 & (-2)(1-x) & -8-x \end{vmatrix} \\ &= (1-x)^2 \begin{vmatrix} \overset{+}{1} & \overset{-}{0} & \overset{+}{-6} \\ 1 & 1 & -3 \\ 0 & -2 & -8-x \end{vmatrix} = (1-x)^2 (-8-x-6+12) \\ &= (1-x)^2 (-2-x). \end{aligned}$$

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### Example

(iii) Compute  $p_{A_3}(x)$  :

$$\begin{aligned} p_{A_3}(x) &= \begin{vmatrix} \mathbf{1-x} & -1 & -1 \\ -1 & \mathbf{1-x} & -1 \\ -1 & -1 & \mathbf{1-x} \end{vmatrix} \begin{array}{cc} c_1 & c_2 \\ \downarrow & \downarrow \\ c_1 - c_2 & c_2 - c_3 \end{array} \\ &= \begin{vmatrix} (2-x) & 0 & -1 \\ -(2-x) & 2-x & -1 \\ 0 & -(2-x) & 1-x \end{vmatrix} \\ &= (2-x)^2 \begin{vmatrix} \overset{+}{1} & \overset{-}{0} & \overset{+}{-1} \\ -1 & 1 & -1 \\ 0 & -1 & 1-x \end{vmatrix} = (2-x)^2 [1-x-1-1] \\ &= -(1+x)(2-x)^2. \end{aligned}$$

Thus,  $p_{A_3}(x) = -(1+x)(2-x)^2$ , and so  $Sp(A) = \{-1, 2\}$ .



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(iii) Compute  $p_{A_4}(x)$  :

$$\begin{aligned} p_{A_4}(x) &= \begin{vmatrix} 4-x & 1 & -1 \\ 2 & 5-x & -2 \\ 1 & 1 & 2-x \end{vmatrix} \begin{array}{cc} 1^{\text{st}} \text{ column} & 2^{\text{nd}} \text{ column} \\ \downarrow & \downarrow \\ 1^{\text{st}} + 3^{\text{rd}} & 2^{\text{nd}} + 3^{\text{rd}} \end{array} \\ &= \begin{vmatrix} (3-x) & 0 & -1 \\ 0 & 3-x & -2 \\ (3-x) & 3-x & 2-x \end{vmatrix} = (3-x)^2 \begin{vmatrix} + & - & + \\ 1 & 0 & -1 \\ 0 & 1 & -2 \\ 1 & 1 & 2-x \end{vmatrix} \\ &= (3-x)^2 (2-x+2+1) \\ &= (3-x)^2 (5-x). \end{aligned}$$

That is,  $p_{A_4}(x) = (3-x)^2 (5-x)$ .

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### Example

Calculate the determinant  $\Delta_n = \begin{vmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & \mathbf{1+x} & 1 & \dots & 1 \\ 1 & 1 & \mathbf{1+x} & \dots & 1 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & 1 & 1 & \dots & \mathbf{1+x} \end{vmatrix}$ . We compute

$\Delta_n$  :

- 1<sup>st</sup> column  $\longrightarrow$  1<sup>st</sup> column
- 2<sup>nd</sup> column  $\longrightarrow$  2<sup>nd</sup> column - 1<sup>st</sup> column
- 3<sup>rd</sup> column  $\longrightarrow$  3<sup>rd</sup> column - 1<sup>st</sup> column, ... and so on. We obtain

$$\Delta_n = \begin{vmatrix} 1 & 0 & 0 & \dots & 0 \\ 1 & \mathbf{x} & 0 & \dots & 0 \\ 1 & 0 & \mathbf{x} & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & 0 & 0 & \dots & \mathbf{x} \end{vmatrix} = x^{n-1}.$$



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### Proposition

Let  $A \in \mathcal{M}_n(\mathbb{R})$  and  $r \in \mathbb{R}^*$ . We have

$$p_{rA}(x) = r^n p_A\left(\frac{x}{r}\right).$$

### Proof.

Indeed, we see that

$$p_{rA}(x) = \begin{vmatrix} ra_{11} - x & ra_{12} & \dots & ra_{1n} \\ ra_{21} & ra_{22} - x & \dots & ra_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ ra_{n1} & ra_{n2} & \dots & ra_{nn} - x \end{vmatrix}$$



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Proof.

$$= \begin{vmatrix} r \left( a_{11} - \frac{x}{r} \right) & ra_{12} & \dots & ra_{1n} \\ ra_{21} & r \left( a_{22} - \frac{x}{r} \right) & \dots & ra_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ ra_{n1} & ra_{n2} & \dots & r \left( a_{nn} - \frac{x}{r} \right) \end{vmatrix}$$

□

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Proof.

and so

$$\begin{aligned} p_{rA}(x) &= r^n \begin{vmatrix} a_{11} - \frac{x}{r} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} - \frac{x}{r} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} - \frac{x}{r} \end{vmatrix} \\ &= r^n p_A\left(\frac{x}{r}\right). \end{aligned}$$

This completes the proof. □

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### Exercise

Consider the vandermonde's determinant <sup>a</sup>:

$$\Delta = \begin{vmatrix} 1 & 1 & 1 \\ a & b & c \\ a^2 & b^2 & c^2 \end{vmatrix}.$$

Prove that  $\Delta = (b - a)(c - a)(c - b)$ , and give a generalization formula.

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<sup>a</sup>In linear algebra, a Vandermonde matrix is a matrix with a geometric progression in each row. It takes its name from the French mathematician Alexandre-Théophile Vandermonde. It is, in particular, used in numerical analysis for solving a system formed by polynomial interpolation.

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### Solution

We have

$$\begin{aligned}\Delta &= \begin{vmatrix} 1 & 1 & 1 \\ a & b & c \\ a^2 & b^2 & c^2 \end{vmatrix} \begin{array}{cc} c_1 & c_2 \\ \downarrow & \downarrow \\ c_2 - c_1 & c_3 - c_2 \end{array} \\ &= \begin{vmatrix} 0 & 0 & 1 \\ b-a & c-b & c \\ b^2-a^2 & c^2-b^2 & c^2 \end{vmatrix} = (b-a)(c-b) \begin{vmatrix} 0 & 0 & 1 \\ 1 & 1 & c \\ b+a & c+b & c^2 \end{vmatrix} \\ &= (b-a)(c-b)(c-a).\end{aligned}$$



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### Fact

In the general case, the **Vendermonde's determinant** is given by

$$\Delta_n = \begin{vmatrix} 1 & 1 & \cdots & 1 \\ x_0 & x_1 & \cdots & x_n \\ x_0^2 & x_1^2 & \cdots & x_n^2 \\ \vdots & \vdots & \cdots & \vdots \\ x_0^n & x_1^n & \cdots & x_n^n \end{vmatrix} = \prod_{i>j} (x_i - x_j).$$

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## Problems

**Ex 01.** Consider the following two matrices:

$$A = \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{pmatrix}, \quad B = \begin{pmatrix} 1 & 1 & 1 \\ 2 & 1 & -1 \\ -3 & 2 & 4 \end{pmatrix}.$$

Calculate  $p_A(x)$  and  $p_B(x)$ . **Ans.**

$$p_A(x) = (1+x)^2(2-x) \quad \text{and} \quad p_B(x) = -(x-2)^3.$$

**Ex 02.** Let  $A$  be the matrix given by

$$A = \begin{pmatrix} 1 & 0 & 0 \\ 1 & 2 & -3 \\ 1 & -1 & 0 \end{pmatrix}.$$

Verify that  $p_A(x) = (x+1)(x-1)(x-3)$ .

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## Problems

Ex 03. Let

$$A = \begin{pmatrix} -3 & 1 & -1 \\ -7 & 5 & -1 \\ -6 & 6 & -2 \end{pmatrix}.$$

Verify that  $p_A(x) = (2+x)^2(4-x)$ .

Ex 04. Let  $A \in \mathcal{M}_n(\mathbb{R})$  be the tridiagonal matrix given by

$$A = \begin{pmatrix} a & b & & \\ c & a & \ddots & \\ & \ddots & \ddots & b \\ & & c & a \end{pmatrix}, \quad a, b, c \in \mathbb{R}.$$

Calculate  $p_A(x)$ .

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## Problems

### Problem

Let  $A$  be the matrix

$$A = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{pmatrix}.$$

Show that  $p_A(x) = x^4 - 1$ . Deduce the eigenvalues of  $A$ .