

# Special Matrices

By

**Bellaouar Djamel**



**University 08 Mai 1945 Guelma**

October 2024

# Special Matrices

## Zero Matrix

### Definition

A matrix with all zero entries is called a **zero matrix** and is denoted by  $0$ . That is,

$$A = \begin{pmatrix} 0 & 0 & \cdots & 0 \\ 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 0 \end{pmatrix}.$$

Also,  $A$  is called the **null matrix**.

# Special Matrices

## Diagonal Matrix

### Definition

A square matrix  $A = (a_{ij})$  is diagonal if  $a_{ij} = 0$  for  $i \neq j$ . In this case, we write  $D = \text{diag} \{ \lambda_1, \lambda_2, \dots, \lambda_n \}$ . So, A **diagonal matrix** is given by:

$$D = \begin{pmatrix} \lambda_1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \lambda_n \end{pmatrix}.$$

- Every computations on diagonal matrices are quite **easy**. For example,  $\sqrt{D}$ ,  $D^k$ ,  $D^{-1}$ ,  $e^D$ ,  $\cos D$ ,  $\ln D$ , ... can be easily computed.

# Special Matrices

## The Identity Matrix

### Definition

The **unit matrix** or the **identity matrix**:

$$I_n = \begin{pmatrix} \mathbf{1} & 0 & \cdots & 0 \\ 0 & \mathbf{1} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \mathbf{1} \end{pmatrix}$$

This is a diagonal matrix; but, all the diagonal elements are equal to 1.

### Fact

For any  $A \in \mathcal{M}_n(\mathbb{R})$  we have

$$A \cdot I_n = I_n \cdot A = A.$$

- We always write  $I$  instead of  $I_n$ . So  $A \cdot I = I \cdot A = A$ .

# Special Matrices

## Upper Triangular Matrix

### Definition

A square matrix is **upper triangular** if all entries below the main diagonal are zero. The general form of an upper triangular matrix is given by

$$U = \begin{pmatrix} \mathbf{a_{11}} & a_{12} & \cdots & a_{1n} \\ 0 & \mathbf{a_{22}} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \mathbf{a_{nn}} \end{pmatrix}.$$

### Definition

A square matrix is **lower triangular** if all entries above the main diagonal are 0. The general form of a lower triangular matrix is given by

$$L = \begin{pmatrix} \mathbf{a}_{11} & 0 & \cdots & 0 \\ a_{21} & \mathbf{a}_{22} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & \mathbf{a}_{nn} \end{pmatrix}.$$

- The eigenvalues of any triangular matrix are its diagonal entries.

# Special Matrices

## Strictly Triangular Matrices

### Definition

**Strictly triangular matrices** are of the form:

$$\begin{pmatrix} \mathbf{0} & a_{12} & \cdots & a_{1n} \\ 0 & \mathbf{0} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \mathbf{0} \end{pmatrix} \text{ or } \begin{pmatrix} \mathbf{0} & 0 & \cdots & 0 \\ a_{21} & \mathbf{0} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & \mathbf{0} \end{pmatrix} .$$

# Special Matrices

## Symmetric Matrices

### Properties of transpose:

- $(A^t)^t = A$ .
- $(A + B)^t = A^t + B^t$ .
- For scalar  $\alpha$ ,  $(\alpha A)^t = \alpha A^t$ .
- $(AB)^t = B^t A^t$ .

### Example

For the matrix

$$A = \begin{pmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{pmatrix} \in \mathcal{M}_{3,2}(\mathbb{R}),$$

we have

$$A^t = \begin{pmatrix} 1 & 3 & 5 \\ 2 & 4 & 6 \end{pmatrix} \in \mathcal{M}_{2,3}(\mathbb{R}).$$

# Special Matrices

## Symmetric Matrices

### Theorem

Let  $A \in \mathcal{M}_n(\mathbb{R})$ . Then  $A$  and  $A^t$  have the same eigenvalues.

### Proof.

Let  $x \in \mathbb{R}$ . We have

$$\begin{aligned} p_A(x) &= \det(A - xI) = \det\left((A - xI)^t\right) \quad (\text{since } \det B = \det B^t) \\ &= \det(A^t - xI) \\ &= p_{A^t}(x). \end{aligned}$$

Thus,  $A$  and its transpose have the same characteristic polynomial. □

### Definition

Let  $A = (a_{ij})_{1 \leq i, j \leq n}$  be a square matrix.  $A$  is said to be **symmetric** if  $A^t = A$ .

That is,  $a_{ij} = a_{ji}$  for each  $i, j \in \overline{1, n}$ . So, an  $n \times n$  matrix  $A$  is called symmetric if it is equal to its transpose.

# Special Matrices

## Symmetric Matrices

### Example

The matrix

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 0 & 5 \\ 3 & 5 & 1 \end{pmatrix}$$

is symmetric; since  $A^t = A$ .

### Corollary

*For every matrix  $A \in \mathcal{M}_n(\mathbb{R})$ ,  $A^t A$  and  $AA^t$  are always symmetric.*

### Proof.

It is clear that

$$(A^t A)^t = A^t (A^t)^t = A^t A.$$

That is, for each  $A \in \mathcal{M}_n(\mathbb{R})$ ,  $A^t A$  is symmetric. □

# Special Matrices

## Symmetric Matrices

### Proposition

*The eigenvalues of a real symmetric matrix are real numbers.*

### Proof.

See Theorem 26. □

### Corollary

Let  $A \in \mathcal{M}_n(\mathbb{R})$  be a symmetric matrix and let  $\alpha_0, \alpha_1, \dots, \alpha_m \in \mathbb{R}$  with  $m \geq 1$ .  
The matrix

$$\alpha_0 I + \alpha_1 A + \dots + \alpha_m A^m$$

*is also symmetric.*

### Proof.

(Easy). □

# Special Matrices

## Skew-symmetric Matrices

### Definition

Let  $A = (a_{ij})_{1 \leq i, j \leq n}$  be a square matrix.  $A$  is said to be **skew-symmetric** if  $A^t = -A$ . That is,  $a_{ij} = -a_{ji}$  for each  $i, j \in \overline{1, n}$ .

For example, the matrix

$$A = \begin{pmatrix} 0 & 2 \\ -2 & 0 \end{pmatrix}$$

is skew-symmetric since  $A^t = -A$ .

### Lemma

*Every square matrix  $M \in \mathcal{M}_n(\mathbb{R})$  can be written as  $A + B$ , where  $A$  is skew-symmetric and  $B$  is symmetric.*

# Special Matrices

## Skew-symmetric Matrices

### Proof.

It is clear that for each  $M \in \mathcal{M}_n(\mathbb{R})$  we have

$$M = \underbrace{\frac{1}{2}(M - M^t)}_{\text{skew-symmetric}} + \underbrace{\frac{1}{2}(M + M^t)}_{\text{symmetric}}.$$



# Special Matrices

## Skew-symmetric Matrices

### Theorem (18)

*Let  $B$  be a skew-symmetric matrix; i.e.,  $B^t = -B$ . Then the matrix  $A = I - B$  is invertible.*

### Remark

*Note that a matrix  $A$  is invertible if and only if  $(Ax = 0 \Rightarrow x = 0)$ .*

# Special Matrices

## Skew-symmetric Matrices

### Proof.

[Proof of Theorem 17]

It suffices to prove that  $Ax = 0$  implies  $x = 0$ . In fact, if  $Ax = 0$ , it follows that  $Bx = x$ . Therefore,

$$\langle x, x \rangle = \langle x, Bx \rangle.$$

On the other hand, we have

$$\begin{aligned}x^t x &= x^t Bx \\ \Rightarrow x^t x &= x^t B^t x \quad (\text{since } (x^t x)^t = x^t x \text{ and } (x^t Bx)^t = x^t B^t x) \\ \Rightarrow x^t x &= x^t (-B) x \quad (\text{since } B \text{ is skew-symmetric}) \\ \Rightarrow x^t x &= -x^t Bx \\ \Rightarrow x^t x &= -x^t x \\ \Rightarrow x^t x &= 0.\end{aligned}$$



# Special Matrices

## Skew-symmetric Matrices

### Proof.

[Proof of Theorem 17]

Setting  $x = (x_1 \ x_2 \ \dots \ x_n)^t$ , we find

$$x^t x = (x_1 \ x_2 \ \dots \ x_n) \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = x_1^2 + x_2^2 + \dots + x_n^2 = 0.$$

Thus,  $x_i = 0$  for each  $i \in \overline{1, n}$ , and so  $x = 0$ . □

1. Let

$$A = \begin{pmatrix} 0 & -2 & 3 \\ 2 & 0 & 4 \\ -3 & -4 & 0 \end{pmatrix}$$

Verify that  $A$  is skew-symmetric.

2. Prove that  $\mathcal{M}_n(\mathbb{R}) = \mathcal{S}_n(\mathbb{R}) \oplus \mathcal{A}_n(\mathbb{R})$ , where  $\mathcal{S}_n(\mathbb{R})$  is the subspace of all symmetric matrices and  $\mathcal{A}_n(\mathbb{R})$  is the subspace of all skew-symmetric matrices.

# Special Matrices

## Orthogonal Matrices

### Definition

A matrix  $A \in \mathcal{M}_n(\mathbb{R})$  is called **orthogonal** if  $A^t = A^{-1}$  (or if  $A^t A = AA^t = I$ ).

### Example

The matrix

$$A = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}; \theta \in \mathbb{R}$$

is orthogonal, since

$$\begin{aligned} A^t A &= AA^t = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix} \\ &= \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = I_2. \end{aligned}$$

# Special Matrices

## Orthogonal Matrices

An orthogonal matrix has the following properties:

1. its column vectors (rows) are orthonormal,
2.  $A^t A = A A^t = I_n$ ,
3.  $A^t = A^{-1}$ ,
4. For every  $x \in \mathbb{R}^n$  :  $\|Ax\| = \|x\|$ ,
5. For every  $x, y \in \mathbb{R}^n$  :  $\langle Ax, Ay \rangle = \langle x, y \rangle$ .

### Corollary

Let  $A \in \mathcal{M}_n(\mathbb{R})$  be an orthogonal matrix. Then  $\det(A) = \pm 1$ .

### Proof.

Since  $A^t = A^{-1}$ , then  $A^t A = I_n$ . It follows that

$$\det(A^t A) = \det(A^t) \det(A) = (\det(A))^2 = \det(I_n) = 1.$$

Hence  $\det(A) = \pm 1$ . □

# Special Matrices

## Orthogonal Matrices

### Theorem

Let  $A \in \mathcal{M}_n(\mathbb{R})$  be an orthogonal matrix. The following properties are equivalent.

- 1)  $A$  is orthogonal.
- 2) For every  $x \in \mathbb{R}^n$  :  $\|Ax\| = \|x\|$ .
- 3) For every  $x, y \in \mathbb{R}^n$  :  $\langle Ax, Ay \rangle = \langle x, y \rangle$ .

### Proof.

1) $\Rightarrow$ 2). Assume that  $A$  is orthogonal. Let  $x \in \mathbb{R}^n$ , we have

$$\|Ax\|^2 = \langle Ax, Ax \rangle = \langle x, A^t Ax \rangle = \langle x, I_n x \rangle = \langle x, x \rangle = \|x\|^2.$$

Therefore,  $\|Ax\| = \|x\|$ .

2) $\Rightarrow$ 3). Assume that  $\forall x \in \mathbb{R}^n$  :  $\|Ax\| = \|x\|$ . Let  $x, y \in \mathbb{R}^n$ , we have

$$\|A(x+y)\|^2 = \|x+y\|^2;$$

# Special Matrices

## Orthogonal Matrices

### Proof.

That is,  $\langle Ax + Ay, Ax + Ay \rangle = \langle x + y, x + y \rangle$ , and so

$$\langle Ax, Ax \rangle + \langle Ay, Ay \rangle + 2 \langle Ax, Ay \rangle = \langle x, x \rangle + \langle y, y \rangle + 2 \langle x, y \rangle$$

Thus,  $\langle Ax, Ay \rangle = \langle x, y \rangle$ .

3) $\Rightarrow$ 1). Assume that  $\forall x, y \in \mathbb{R}^n : \langle Ax, Ay \rangle = \langle x, y \rangle$ . It follows that

$$\langle x, A^t Ay \rangle = \langle x, y \rangle$$

i.e.,  $\langle x, A^t Ay - y \rangle = 0$ . In particular, for  $x = A^t Ay - y$ , we obtain

$$\|A^t Ay - y\|^2 = 0.$$

Hence  $A^t Ay = y$ , and therefore  $A^t A = I_n$ . □

### Exercise

Consider the matrix

$$A = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

For each  $\theta \in \mathbb{R}$ , prove that  $e^{\theta A}$  is orthogonal<sup>a</sup>.

---

<sup>a</sup>See the chapter of exponential of square matrices.

### Exercise

Let  $A$  be an orthogonal matrix. Prove the following properties:

- 1  $A^{-1}$  is orthogonal.
- 2 For every  $\lambda \in Sp(A) \Rightarrow |\lambda| = 1$ .
- 3 If  $A_1$  and  $A_2$  are two orthogonal matrices, then  $A_1 A_2$  is also orthogonal.

# Special Matrices

## Hermitian Matrices

### Definition

Let  $A = (a_{ij})_{1 \leq i, j \leq n} \in \mathcal{M}_n(\mathbb{C})$ . That is  $a_{ij}$  is a complex number for  $1 \leq i, j \leq n$ . The matrix  $(\overline{a_{ij}})_{1 \leq i, j \leq n}$  is called **conjugate** of  $A$ , denoted by  $\overline{A}$ . The **transpose conjugate** matrix of  $A$  is called the **adjoint** of  $A$ , denoted by  $A^*$ . Note that  $A^* = \overline{A^t} = (\overline{A})^t$ .

### Definition

A matrix  $A \in \mathcal{M}_n(\mathbb{C})$  is called **Hermitian**<sup>a</sup> if  $A^* = A$ . That is, if  $\overline{A^t} = A$ .

<sup>a</sup>On the other hand, a matrix  $A$  is said to be skew-Hermitian if  $A^* = -A$ .

# Special Matrices

## Hermitian Matrices

### Example

The matrix

$$A = \begin{pmatrix} 1 & 1+i & 2+3i \\ 1-i & -2 & -i \\ 2-3i & i & 0 \end{pmatrix}$$

is Hermitian; because  $A^* = A$ .

### Proposition

*The diagonal coefficients of a Hermitian matrix are real.*

### Proof.

From Definition 22, the result is obvious since  $a_{ii} = \overline{a_{ii}}$  for  $1 \leq i \leq n$ .

### Remark

*Let  $A \in \mathcal{M}_n(\mathbb{C})$ . We can easily prove that  $A + A^*$ ,  $AA^*$  and  $A^*A$  are Hermitian.*

### Theorem

*The eigenvalues of a Hermitian matrix are real.*

**Proof.** Let  $(\lambda, x)$  be an eigenpair of a Hermitian matrix  $A$  (note that  $x \neq 0$ ). We can write

$$\begin{aligned}\lambda \langle x, x \rangle &= \langle \lambda x, x \rangle \\ &= \langle Ax, x \rangle = (Ax)^t \bar{x} = x^t A^t \bar{x} \\ &= x^t \left( (\bar{A})^t \right)^t \bar{x} \quad (\text{since } (\bar{A})^t = A) \\ &= x^t \bar{A} \bar{x} = x^t \overline{Ax} = \langle x, Ax \rangle = \langle x, \lambda x \rangle = \bar{\lambda} \langle x, x \rangle.\end{aligned}$$

That is,  $\lambda = \bar{\lambda}$ .

# Special Matrices

## Unitary Matrices, Normal Matrices

### Definition

A matrix  $U \in \mathcal{M}_n(\mathbb{C})$  is said to be **unitary** if  $U^{-1} = U^*$ . In other words, a square matrix  $U$  with complex coefficients is said to be unitary if it satisfies the equalities:

$$U^*U = UU^* = I_n.$$

- The unitary matrices with real coefficients are the orthogonal matrices.
- Note that a complex square matrix  $A$  is **normal** if it commutes with its conjugate transpose  $A^*$ . That is,  $A^*A = AA^*$ . Thus, unitary, Hermitian and skew-Hermitian matrices are normal.

### Example

The matrix

$$A = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$$

is unitary; since

$$AA^* = A^*A = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = I_2.$$

# Special Matrices

## Unitary Matrices

Any unitary matrix  $U$  satisfies the following properties:

- a. its determinant has modulus 1;
- b. its eigenvectors are orthogonal;
- c.  $U$  is diagonalizable, i.e.,

$$U = VDV^*,$$

where  $V$  is a unitary matrix and  $D$  is a unitary diagonal matrix.

- d.  $U$  can be written as an exponential of a matrix:

$$U = e^{iH},$$

where  $i$  is the imaginary unit and  $H$  is a Hermitian matrix.

### Proposition

Let  $U$  be a square matrix of size  $n$  with complex coefficients; the following five propositions are equivalent:

- 1  $U$  is unitary;
- 2  $U^*$  is unitary;
- 3  $U$  is invertible and its inverse is  $U^*$ ;
- 4 the columns of  $U$  form an orthonormal basis for the canonical Hermitian product over  $\mathbb{C}^n$ ;
- 5  $U$  is normal and its eigenvalues have modulus 1.

# Special Matrices

## Idempotent matrices

### Definition

Let  $A \in \mathcal{M}_n(\mathbb{K})$ . Then  $A$  is called **idempotent** if  $A^2 = A$ .

Examples of  $2 \times 2$  idempotent matrices are:

$$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 3 & -6 \\ 1 & -2 \end{pmatrix}$$

### Theorem

*If  $A$  is idempotent, then  $A$  is diagonalizable.*

### Proof.

Since  $A^2 = A$ , it follows that  $m_A(x) = x(x-1)$  which has simple roots, and hence  $A$  is diagonalizable. □